

### **LISTING OF THE CLAIMS**

The following listing of the claims is un-amended and provided for the Examiner's convenience:

**Claim 1 (original):** A vehicle drive assist system, comprising:

frontal circumstances recognizing means for recognizing a solid object in front of an own vehicle based on images taken by imaging means;

oncoming lane crossing intension detecting means for detecting an intension of said own vehicle to cross an oncoming lane;

oncoming waiting vehicle detecting means for detecting an oncoming vehicle waiting in front of said own vehicle on said oncoming lane;

oncoming straight vehicle detecting area establishing means for establishing a detecting area in the vicinity of said oncoming vehicle waiting; and

oncoming straight vehicle detecting means for detecting an oncoming vehicle traveling straight in said detecting area.

**Claim 2 (original):** The vehicle drive assist system according to claim 1, wherein said oncoming lane crossing intension detecting means detect an intension of said own vehicle to cross said oncoming lane when said own vehicle travels at a low speed and when a turn signal switch is turned on.

**Claim 3 (original):** The vehicle drive assist system according to claim 1, wherein said oncoming waiting vehicle detecting means recognize an oncoming vehicle as an oncoming vehicle waiting when said oncoming vehicle exists within a predetermined distance in front of said own vehicle and when said oncoming vehicle travels at a low speed toward said own vehicle and when said oncoming vehicle is detected successively on several frames of said images.

**Claim 4 (original):** The vehicle drive assist system according to claim 1, wherein said oncoming straight vehicle detecting means recognize an oncoming vehicle as an oncoming vehicle traveling straight when a new solid object appears in said detecting area and when only a portion on an oncoming lane side of said new solid object is detected.

**Claim 5 (original):** The vehicle drive assist system according to claim 1, wherein when another solid object always exists in said detecting area, a new detecting area is established on the oncoming lane side of said other solid object and said detecting area is substituted with said new detecting area.

**Claim 6 (original):** The vehicle drive assist system according to claim 1, further comprising: warning means for warning a driver of said own vehicle when said oncoming vehicle traveling straight is detected.